Finitely presented groups 1

Max Neunhöffer



LMS Short Course on Computational Group Theory 29 July – 2 August 2013

$$\langle C \mid C^k = 1 \rangle$$

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 $\langle D, E, F | DEFED, EFD, D^2EF \rangle$ is the trivial group {1}.

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- $uv \sim uxx^{-1}v$ for all $u, v \in \hat{X}^*$ and all $x \in \hat{X}$, and
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Definition/Proposition (Finitely presented group)

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 $f(x_1) \cdot f(x_2) \cdot \cdots \cdot f(x_k) = 1 \in H \qquad (*)$

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 $\langle C | C^k \rangle$ has all cyclic groups of order *o* dividing *k* as quotients.

Problem (Word problem (Dehn 1911))

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We would like to have algorithms for these decision problems

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for a $k \in \mathbb{N}$ and some $w_i \in \hat{X}^*$ and $r_i \in R \cup R^{-1}$.

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For w with $\overline{w} = 1$ let A(w) be the minimal such k.

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Definition (Dehn function)

$$\delta(\ell) := \max\{A(w) \mid w \in \hat{X}^* \text{ of length } \ell \text{ and } \overline{w} = 1\}$$

Theorem (Novikov 1955, Boone 1958)

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Nevertheless, in GAP you can work with finitely presented groups:

http://tinyurl.com/MNGAPsess/GAP_FP_1.g

Max Neunhöffer (University of St Andrews)

Finitely presented groups 1

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All these steps are called "Tietze transformations", they change the presentation, but not the isomorphism type of the group.

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Proposition

If $\varphi: G \to A$ is any group homomorphism to an abelian group A, then there is a unique group homomorphism $\tilde{\varphi} : G/G' \to A$ with $\varphi = \pi \tilde{\varphi}$:



where $\pi: G \to G/G'$ is the natural map.

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If $\varphi: G \to A$ is any group homomorphism to an abelian group A, then there is a unique group homomorphism $\tilde{\varphi} : G/G' \to A$ with $\varphi = \pi \tilde{\varphi}$:



where $\pi : G \rightarrow G/G'$ is the natural map.

(Note $G' \subset \ker \varphi$)

The rest of this talk is about studying G/G' where $G = \langle X | R \rangle$ and G' is the derived subgroup.

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We immediately get:

$$G/G' \cong H := \left\langle X \mid R, \{xyx^{-1}y^{-1} \mid x, y \in X\} \right\rangle$$

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That is, *H* as quotient of \mathbb{Z}^n is described by a matrix

$$M := \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_k \end{bmatrix} \in \mathbb{Z}^{k \times n}$$

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If $N := S \cdot M \cdot T$ is the Smith normal form of M (with S, T invertible), then $H \cong \mathbb{Z}^n/(\text{row space of } N)$ and we can read off the structure.

$$N = \begin{bmatrix} 1 & \cdot & \cdot & \cdot & \cdot \\ \cdot & 2 & \cdot & \cdot & \cdot \\ \cdot & \cdot & 6 & \cdot & \cdot \\ \cdot & \cdot & \cdot & 0 & \cdot \end{bmatrix} = S \cdot M \cdot T,$$

then $H \cong \mathbb{Z}/(2\mathbb{Z}) \oplus \mathbb{Z}/(6\mathbb{Z}) \oplus \mathbb{Z} \oplus \mathbb{Z}$.

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The matrix *S* recombines the rows of *M* (changing the generators of the row space) and the matrix *T* changes the generating set of \mathbb{Z}^n . Both manipulations can be traced explicitly, yielding an explicit, computable isomorphism

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The diagonal entries d_1, d_2, \ldots, d_k fulfill $d_1 \mid d_2 \mid \cdots \mid d_r$ and $d_{r+1} = 0 = d_{r+2} = \cdots = d_k$ for some *r* and are called the invariant factors or abelian invariants of *G*.

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GAP can do all this:

http://tinyurl.com/MNGAPsess/GAP_FP_3.g

Max Neunhöffer (University of St Andrews)

Finitely presented groups 1